

# BTF-Specification

## Version History

| Version | Author                                     | Datum      | Description  |
|---------|--|------------|--|
| V1.0    | [Timing-Architects]                        | 2011-07-18 | Initial specification approved with thanks by Continental Automotive GmbH, extended by source-entity-instance column |
| V2.0    | [Timing-Architects]                        | 2012-04-17 | Added new data types   |
| V2.0.1  | [Timing-Architects]                        | 2013-03-29 | Added state charts and description of all entities   |
| V2.0.2  | [Timing-Architects]                        | 2013-04-22 | First public release   |
| V2.1.0  | [Timing-Architects]<br>[Robert Bosch GmbH] | 2013-06-18 | - Changed Process State Chart for compliance to OSEK 2.2.3 Extended Task Model<br>- Some improvements of description |
| V2.1.1  | [Timing-Architects]                        | 2013-10-30 | Clarified description and examples regarding difference preempt/suspend for processes/runnables.                     |
| V2.1.3  | [Timing-Architects]                        | 2014-04-10 | Process state chart: changed layout according to OSEK state order. First published version.                          |

*Note: In version key V x.x.y, x represents change in BTF, y is only specification update.*

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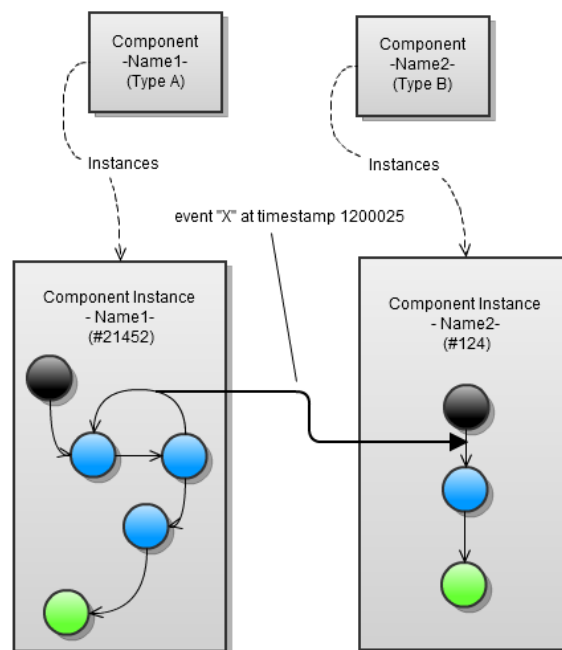
## 1. INTRODUCTION

This document specifies a tracing format for timing evaluation of event based systems. The BTF (Best Trace Format, originating from Better Trace Format (BTF V1.0)) is a CSV-based format for representation of event-traces in ASCII. BTF is a format definition for full scale timing traces of simulator and profiling tools.

The Best Trace Format (BTF) is based on the Better Trace Format, initially defined by Continental Automotive GmbH. It allows analyzing the behavior of a system in a chronologically correct manner in order to apply timing, performance, or reliability evaluations. In general, it assumes a signal processing system, where one component of the system notifies another component of the system. These notifications are realized by events, stored in the BTF file. In comparison with compact trace formats from debugger traces, a BTF log of an event includes the entire information, namely: which component interacts with which component by an event.

Advanced scheduling concepts may be used in multicore processor systems where one traced component may have multiple instances at the same time, i.e. global scheduling or task migration concepts. This requires instance identification in order to derive which instance of a component is addressed in the event log. This means for example that each task execution can be exactly identified for the complete lifetime from activation till termination by its component name and instance counter.

The following figure shows the interaction between two component instances, where component Name1 (Instance #21452) sends an event X to component Name2 (Instance #124) at  $t=1200025$ . A component instance is generated from its parent component and duplicates its behavior (e.g. execution time according to a certain sequence). Nevertheless, it may be possible that a component instance exists over the complete traced time interval.



**FIGURE 1: SCHEMATIC VISUALIZATION OF INTERACTION BETWEEN TWO ENTITY INSTANCES.**

## 2. STRUCTURE OF BTF-FILE

A BTF-file consists of two parts:

1. A header-section, containing meta-information on objects of the trace and optional comments.

All lines start with a `#`. The meta-information is described by pragma-statements (see Section 2.1.2). Comments contain directly after the `#`-symbol a space, which allows the differentiation from pragma-statements.

2. A data-section, containing the trace-data of the simulation or measurement.

The data-section consists of lines in CSV format with optional comment-lines. Each line represents one event of the traced system. The columns of the event-line describe the time, entities, and event. Comments are defined as in the header-section.

For the representation of the data-sections two ways exist. The symbolic-mode describes entities and event by names. The numeric-mode describes entities and event by a numerical identifier. In this case, the header-section includes the mapping between numerical identifier and a string of the name.

### 2.1. HEADER

The header includes parameters, used for the interpretation of the trace or information of the trace generator, and comments. Parameters and comments are indicated by a `#`-symbol.

The typical header of a BTF-file includes at least the version, creator, creation date and the time scale. Further information is optional.

#### 2.1.1. COMMENTS

Each row, starting with a `#`-symbol which is followed with a whitespace is a parameter. Comments can be part of the header or can be entered at any position of the data section.

#### 2.1.2. PARAMETERS

Each row, starting with a `#`-symbol and one of the following parameter definitions is a parameter.

The parameter definition may not start with a whitespace. When the symbol `-` follows the `#` symbol, the row is an entry of the last defined table (e.g. typeTable). Following parameter definitions are predefined:

**TABLE 1: PARAMETERS FOR BTF HEADER SECTION**

| Parameter                  | Description  | Type              | Example   |
|----------------------------|--|-------------------|---|
| <code>#version</code>      | Version of BTF format definition   | String            | <code>#version 1.0</code>                           |
| <code>#creator</code>      | Name and version of the program or device, which generated the trace   | String            | <code>#creator TA-Simulator (12.10.2.47)</code>     |
| <code>#creationDate</code> | Timestamp of the start of simulation or measurement. The format has to comply with "ISO 8601 extended specification for representations of dates | String (ISO 8601) | <code>#creationdate<br/>2012-09-02T16:40:30Z</code> |

|                      |  |                                      |  |
|----------------------|--|--------------------------------------|--|
|                      | and times" YYYY-MM-DDTHH:MM:SS. The time should be in UTC time (indicated by a "Z" at the end)   |                                      |  |
| #inputFile           | Filename of the model which was used for the simulation  | String (URI)                         | #inputFile<br>D:\Workspace\Project\DualCore.rte  |
| #timescale           | Defines the resolution of the timestamps in the trace. Default unit is nano-seconds (ns).  | String (Enumeration [ps,ns,us,ms,s]) | #timescale ns  |
| #typeTable           | Indicates the beginning of a mapping from all entities to a numerical Type-Id. See Table 3 for existing types.<br><br>Type-Ids start with 0. Missing Ids are allowed               | -<n> String                          | #entityType<br><br>#-0 T<br><br>#-1 R<br><br>#-2 SIG   |
| #entityTable <n>     | Indicates the beginning of a mapping from all entities to a numerical Entity-Id. An entity can be a task, runnable, etc.<br><br>Type-Ids start with 0 and some Ids can be missing. | -<n> String                          | #entityTable<br><br>#-0 Task_1ms<br><br>#-1 GetSignal<br><br>#-2 Main<br><br>#-3 Temperature       |
| #entityTypeTable <n> | Indicates the beginning of a mapping from all entities to types. Both, entity and type has to be defined before in the entityTable and entityTable.                                | -<n> String                          | #entityTypeTable<br><br>#-T Task_1ms<br><br>#-R GetSignal<br><br>#-R Main<br><br>#-SIG Temperature |

**Example:**

A typical header can look in the following way:

```
#version 1.0
#creator TA-Toolsuite 12.06.1
# Simulation of dualcore processor 120MHz, 16Kbyte RAM
#creationDate 2012-08-31T15:53:00
#inputFile c:\TAsc\doc\examples\lems.tap
#timeScale ns
#entityType
#-0 T
#-1 R
#entityTable
#-0 Task_1ms
#-1 Task_2ms
#-2 Runnable_1ms_Init
#-3 Runnable_2ms_Store
#-4 Runnable_2ms_Read
#entityTypeTable
#-T Task_1ms
#-T Task_2ms
#-R Runnable_1ms_Init
#-R Runnable_2ms_Store
#-R Runnable_2ms_Read
```

## 2.2. DATA SECTION

The trace information is represented in CSV format. Each line describes one event. The interpretation of one line depends on the event type, shown in the next section.

For separating the content of one line the symbol ',' (comma) is used. For the case using floating numbers, a '.' (point) has to be used as decimal separator. Strings can be written between quotation marks '"'. For strings with space characters writing in quotation marks is forced.

At any point of the trace section, a comment with pragma '#' can be written.

## 2.3. ENTITIES AND EVENTS

The data section consists of line by line interpreted data. Each line has eight columns, whereas the last column is optional. A line contains the following elements:

<Time>,<Source>,<SourceInstance >,<TargetType>,<Target>,<TargetInstance>,<Event>,<Note>

The interpretation of the different columns depends on the <TargetType>-column.

**TABLE 2: DESCRIPTION OF BTF COLUMNS**

| Column | Name           | Description   | Relevant for entity type |
|--------|----------------|---|--------------------------|
| 1      | Time           | Integer timestamp for one action. The timescale is given in the configuration section by the parameter #timescale.  | all                      |
| 2      | Source         | Unique name for the source which triggers the event.<br><br>(e.g. Core at start of a task or stimulus at the activation of a task)  | all                      |
| 3      | SourceInstance | Instance counter for the source. Non-instanceable entities (e.g. core) have each time the instance '-1'. Instanceable entities like stimuli starting with 0 and increment at each instantiation the counter. If there is no information for the instance this field can be empty. | all                      |
| 4      | Type           | Type of the event target.   | all                      |
| 5      | Target         | Unique name for the target, which triggers the event (e.g. a task, runnable, signal-access).  | all                      |
| 6      | TargetInstance | Instance counter for the target.  | all                      |
| 7      | Event          | Name of the event   | all                      |
| 8      | Note           | Optional field for further information (e.g. signal value at signal read or write access)   | SIG, SEM                 |

The fourth column (<TargetType>) includes the type of the event. Following types are defined in the BTF:

**TABLE 3: ENTITY TYPES.**

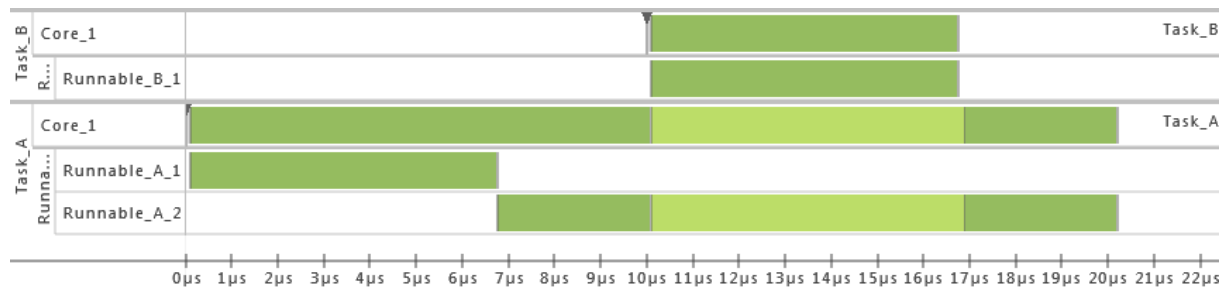
| Category                | Type-ID | Name   | Description  |
|-------------------------|---------|--|--|
| <i>Environment</i>      |         |  |  |
|                         | STI     | Stimulus   | Trigger point for a Task or ISR  |
| <i>Software</i>         |         |  |  |
|                         | T       | Task<br>(Specialization of Process)                      | Object handled by OS Scheduler, and calling all "Top-Level" Runnables. A Task is the specialization of a Process type.             |
|                         | ISR     | Interrupt-Service-Routine<br>(Specialization of Process) | Object handled by Interrupt-Management Unit and calling all "Top-Level" Runnables. An ISR is the specialization of a Process type. |
|                         | R       | Runnable   | Object, called by a Process or another Runnable.   |
|                         | IB      | Instruction block  | Sub-fraction of a Runnable   |
| <i>Hardware</i>         |         |  |  |
|                         | ECU     | Electronic Control Unit                                  | Hardware device which has at least one processor.  |
|                         | P       | Processor  | Hardware device which has at least one core  |
|                         | C       | Core   | Hardware device which is part of a processor and executes software.  |
| <i>Operating System</i> |         |  |  |
|                         | SCHED   | Scheduler  | Part of operating system which assigns processes to cores.   |
|                         | SIG     | Signal   | Shared data object (e.g. variable) in a software.  |
|                         | SEM     | Semaphore  | Operating system object, for restricting access to resources.  |
| <i>Information</i>      |         |  |  |
|                         | SIM     | Simulation   | Used for notification events from simulation environment, e.g. simulation started or simulation stopped.                           |



**Example:**

|        |         |    |    |               |    |           |
|--------|---------|----|----|---------------|----|-----------|
| 0,     | Task_A, | 0, | T, | Task_A,       | 0, | activate  |
| 100,   | Core_1, | 0, | T, | Task_A,       | 0, | start     |
| 100,   | Task_A, | 0, | R, | Runnable_A_1, | 0, | start     |
| 6766,  | Task_A, | 0, | R, | Runnable_A_1, | 0, | terminate |
| 6766,  | Task_A, | 0, | R, | Runnable_A_2, | 0, | start     |
| 10000, | Task_B, | 0, | T, | Task_B,       | 0, | activate  |
| 10100, | Task_A, | 0, | R, | Runnable_A_2, | 0, | suspend   |
| 10100, | Core_1, | 0, | T, | Task_A,       | 0, | preempt   |
| 10100, | Core_1, | 0, | T, | Task_B,       | 0, | start     |
| 10100, | Task_B, | 0, | R, | Runnable_B_1, | 0, | start     |
| 16766, | Task_B, | 0, | R, | Runnable_B_1, | 0, | terminate |
| 16766, | Core_1, | 0, | T, | Task_B,       | 0, | terminate |
| 16866, | Core_1, | 0, | T, | Task_A,       | 0, | resume    |
| 16866, | Task_A, | 0, | R, | Runnable_A_2, | 0, | resume    |
| 20199, | Task_A, | 0, | R, | Runnable_A_2, | 0, | terminate |
| 20199, | Core_1, | 0, | T, | Task_A,       | 0, | terminate |

**Gantt-Chart of Example**



**FIGURE 2: GANTT CHART OF EXAMPLE. DARK GREEN AREAS SHOW EXECUTION OF TASK OR RUNNABLE. LIGHT GREEN AREAS SHOW TASKS/RUNNABLES IN PREEMPT/SUSPENDED STATE.**

**2.3.1. STIMULUS-EVENTS**

A stimulus is used to model external inputs or internal behavior, which is not modeled by other software or hardware parts. A stimulus is able to activate a task/ISR or set a signal value.

**TABLE 4: COLUMNS FOR STIMULUS ENTITY.**

| Column   | Entries                                 |
|----------|---|
| <Source> | Simulation (SIM), Task (T) or ISR (ISR) |
| <Event>  | trigger                                 |

**Example:**

|          |                       |     |      |                    |    |         |
|----------|-----------------------|-----|------|--------------------|----|---------|
| 1200150, | TASK_InputProcessing, | 0,  | STI, | IPA_InputReady,    | 0, | trigger |
| 1200237, | SIM,                  | -1, | STI, | IR_SCHED_Tasks_C1, | 7, | trigger |
| 1222581, | SIM,                  | -1, | STI, | IR_SCHED_Tasks_C1, | 8, | trigger |
| 2239187, | TASK_InputProcessing, | 1,  | STI, | IPA_InputReady,    | 1, | trigger |
| 2250000, | SIM,                  | -1, | STI, | TIMER_1ms,         | 2, | trigger |

### 2.3.2. PROCESS-EVENTS (TASK- AND ISR-EVENTS)

A process can be either a task or an interrupt service routine. A process is activated by a stimulus, as described in section 2.3.1. After activation, a scheduler assigns the process to a core where the process is executed. A running process can be preempted by another process and change to READY. Alternatively, a cooperative process can change itself to READY, e.g. at a schedule point or explicit migration to another core. When a running process requests a resource (e.g. semaphore or event) which is not available, the process waits actively (e.g. “while(ResourceNotAvailable){...}”). This is indicated by the state POLLING. The scheduler could decide to remove a waiting process from the core and the process changes in state PARKING (passive waiting). When the requested resource becomes available but the process is in state parking, the process changes again to state READY.

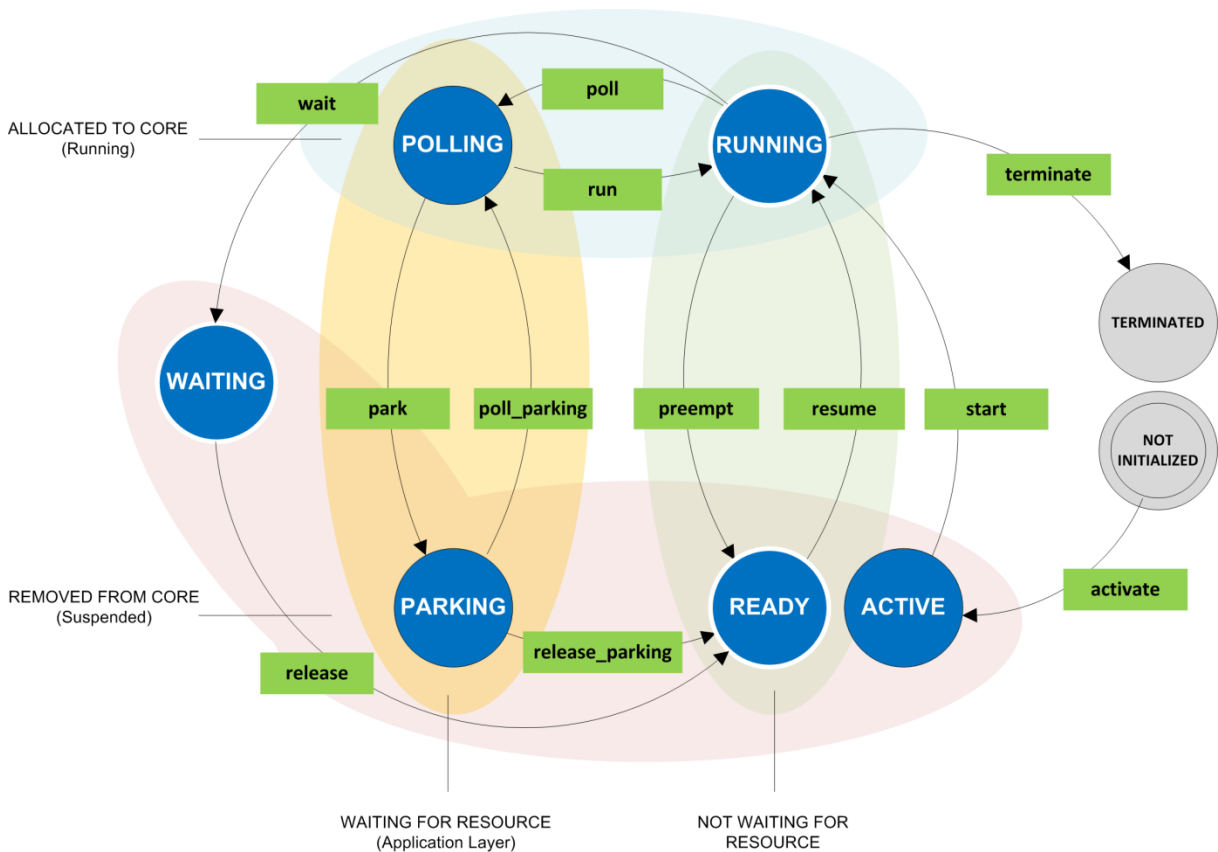


FIGURE 3: PROCESS STATE CHART.

**Note:** Whenever process (P) is used in the following description, this can either be a task (T) or interrupt-service-routine (ISR)

TABLE 5: COLUMNS FOR PROCESS ENTITY.

| Column   | Entries  |
|----------|--|
| <Source> | Stimulus (STI), Core (C), process (P)  |
| <Event>  | activate, start, preempt, resume, terminate, poll, run, park, poll_parking, release_parking, wait, release, deadline, mpalimitexceeded, boundedmigration, phasemigration, fullmigration, enforcedmigration |

**TABLE 6: STATES FOR PROCESS ENTITY.**

| State      | Description  |
|------------|--|
| ACTIVE     | When instance is ready for execution   |
| RUNNING    | When instance executes on a core   |
| READY      | When instance was preempted  |
| WAITING    | When instance has requested an OS Event which is not available and waits passively |
| POLLING    | When instance has requested a resource which is not available and waits actively   |
| PARKING    | When instance waits for a not available resource and is preempted                  |
| TERMINATED | When instance was finished execution   |

**TABLE 7: EVENTS FOR PROCESS ENTITY.**

| Internal Event  | Description   | Source        |
|-----------------|---|---------------|
| ACTIVATE        | Process instance is activated by a stimulus   | STI, P        |
| START           | Process instance is allocated to the core and starts execution for the first time   | C             |
| PREEMPT         | Executing process instance is stopped by the scheduler, e.g. because of a higher priority process which is activated.                         | C             |
| RESUME          | Preempted process instance continues execution on the same or other core.   | C             |
| TERMINATE       | Process instance has finished execution   | C             |
| POLL            | Process instance has requested a resource by polling (active waiting) which is not available  | C             |
| RUN             | Process instance resumes execution after polling (i.e. active waiting) for a resource   | C             |
| PARK            | Active waiting process instance is preempted by another process.  | C             |
| POLL_PARKING    | Parking process instance is allocated to the core and again polls (i.e. actively waits) for a resource.                                       | C             |
| RELEASE_PARKING | Resource which is requested by parking process instance becomes available, but parking process stays preempted and changes to READY state.    | C (last Core) |
| WAIT            | Process has requested a non-set OS EVENT (see OSEK 2.2.3 Extended Task Model, WAIT_Event() ).   | C (last Core) |
| RELEASE         | OS EVENT which was requested by a process is set (see OSEK 2.2.3 Extended Task Model, SET_Event()) and process is ready to proceed execution. | C (last Core) |

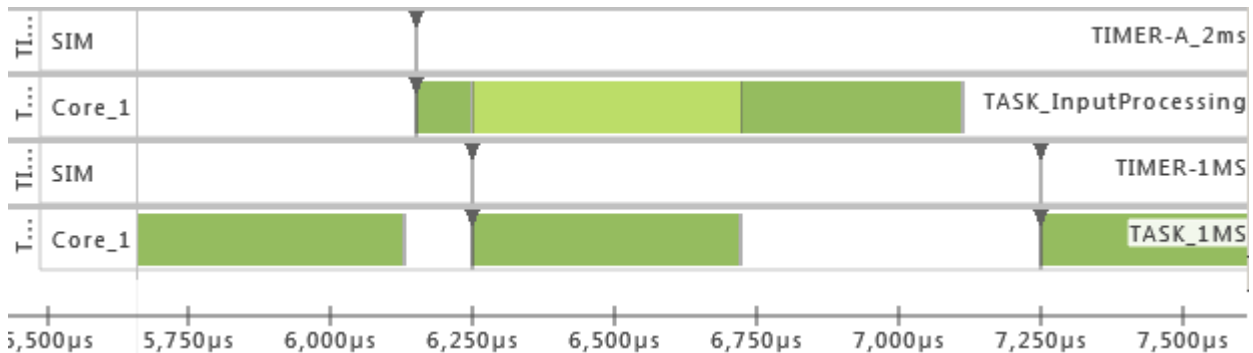
**TABLE 8: INFO EVENTS FOR PROCESS ENTITY.**

| Notification-Event | Description  |
|--------------------|--|
| MPALIMITEXCEEDED   | When there are more process instances of this process as the MPA-LIMIT value (MPA = MultipleProcessActivation)                                 |
| BOUNDEDMIGRATION   | When last executing core of previous instance is not equal to first executing core of this instance.   |
| PHASEMIGRATION     | When the executing core before a preemption is not equal to the new executing core and there is no schedule point right before this execution. |
| FULLMIGRATION      | When the executing core before a preemption is not equal to new executing core and there is a schedule point right before this execution.      |
| ENFORCEDMIGRATION  | When a process migrates at a predefined position in execution to another scheduler.  |

**Example:**

The example shows the activation of TASK\_InputProcessing, triggered by a timer. TASK\_InputProcessing starts execution and is preempted by task TASK\_1MS, also triggered by a timer. After TASK\_1MS has finished execution, TASK\_InputProcessing resumes execution.

|          |              |    |      |                       |     |           |
|----------|--------------|----|------|-----------------------|-----|-----------|
| 6150000, | TIMER-A_2ms, | 3, | T,   | TASK_InputProcessing, | 3,  | activate  |
| 6150100, | Core_1,      | 0, | T,   | TASK_InputProcessing, | 3,  | start     |
| 6250000, | TIMER-1MS,   | 6, | T,   | TASK_1MS,             | 6,  | activate  |
| 6250100, | TASK_1MS,    | 6, | STI, | IR_SCHED_Tasks_C1,    | 24, | trigger   |
| 6250100, | Core_1,      | 0, | T,   | TASK_InputProcessing, | 3,  | preempt   |
| 6250100, | Core_1,      | 0, | T,   | TASK_1MS,             | 6,  | start     |
| 6721825, | Core_1,      | 0, | T,   | TASK_1MS,             | 6,  | terminate |
| 6721925, | Core_1,      | 0, | T,   | TASK_InputProcessing, | 3,  | resume    |
| 7110175, | Core_1,      | 0, | T,   | TASK_InputProcessing, | 3,  | terminate |



**FIGURE 4: GANTT CHART OF EXAMPLE. DARK GREEN AREAS SHOW EXECUTION OF TASK. LIGHT GREEN AREAS SHOW TASKS IN PREEMPT STATE.**

### 2.3.3. RUNNABLE EVENTS

A runnable is called within a process instance or in the context of another runnable. When a runnable is called, it starts and changes to RUNNING. When the process instance which includes the runnable is suspended, the runnable itself is also suspended and changes to state SUSPENDED. When the process instance is resumed, the runnable also changes to RUNNING. After complete execution, the runnable changes to TERMINATED.

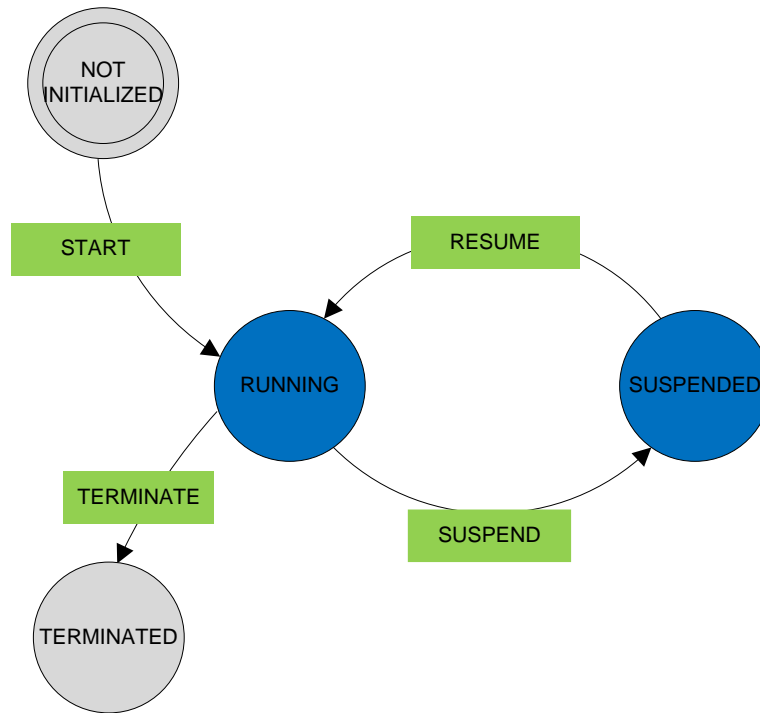


FIGURE 5: RUNNABLE STATE CHART.

TABLE 9: COLUMNS FOR RUNNABLE ENTITY.

| Column   | Entries                           |
|----------|-----------------------------------|
| <Source> | Process (P)                       |
| <Event>  | start, suspend, resume, terminate |

TABLE 10: STATES FOR RUNNABLE ENTITY.

| State     | Description  |
|-----------|--|
| RUNNING   | Runnable instance executes on a core               |
| SUSPENDED | Runnable instances has stopped execution on a core |

**TABLE 11: EVENTS FOR RUNNABLE ENTITY.**

| Events    | Description   | Source |
|-----------|---|--------|
| START     | Runnable instance is allocated to the core and starts execution for the first time. | P      |
| SUSPEND   | Executing runnable instance is stopped, because the calling process is suspended.   | P      |
| RESUME    | Suspended runnable instance continues execution on the same or other core.          | P      |
| TERMINATE | Runnable instance has finished execution.   | P      |

The runnable R\_T20\_O2 is started and preempted by runnable R\_T1\_Init. After termination of R\_T1\_Init, runnable R\_T20\_O2 resumes execution.

|          |            |    |    |            |    |            |
|----------|------------|----|----|------------|----|------------|
| 3232706, | TASK_20MS, | 0, | R, | R_T20_O2,  | 0, | start,     |
| 3250100, | TASK_20MS, | 0, | R, | R_T20_O2,  | 0, | suspend,   |
| 3250100, | TASK_1MS,  | 3, | R, | R_T1_Init, | 3, | start,     |
| 3326368, | TASK_1MS,  | 3, | R, | R_T1_Init, | 3, | terminate, |
| 3714350, | TASK_20MS, | 0, | R, | R_T20_O2,  | 0, | resume,    |
| 3740812, | TASK_20MS, | 0, | R, | R_T20_O2,  | 0, | terminate, |

### 2.3.4. SIGNAL-EVENTS

A signal is a label, which can be accessed by a process instance.

**TABLE 12: COLUMNS FOR SIGNAL ENTITY.**

| Column   | Entries                     |
|----------|-----------------------------|
| <Source> | Process (P), Stimulus (STI) |
| <Event>  | read, write                 |

**TABLE 13: EVENTS FOR SIGNAL ENTITY.**

| Events | Description                                  | Source |
|--------|--|--------|
| READ   | Signal is read by a process                  | P      |
| WRITE  | Signal is written by a process or a stimulus | P, STI |

#### **Example:**

|          |                       |    |      |                |    |          |
|----------|-----------------------|----|------|----------------|----|----------|
| 1222481, | STI_MODE_SWITCH,      | 0, | SIG, | HighPowerMode, | 0, | write, 1 |
| 1222481, | TASK_200MS,           | 0, | SIG, | HighPowerMode, | 0, | read, 1  |
| 4482566, | TASK_WritingActuator, | 2, | SIG, | S16_C1_1,      | 0, | write, 0 |
| 5590428. | TASK_10MS.            | 0. | SIG. | S16_C1_1.      | 0. | read. 0  |