# **OPENPASS**



# **TARGET OBJECTIVES**



openPASS (open Platform for Assessment of Safety Systems) High level of transparency and acceptance through publicly available open source platform



**Traffic simulation** of highway, rural and urban scenarios

Stochastic variation of scenarios





Standardized interfaces for model integration

**Reproducibility** through deterministic simulation



Harmonized and flexible platform for effectiveness assessment of advanced driver assistance systems and automated driving

### **WORKING GROUP**





# **PLATFORM CONCEPT**





\* Simple examples are provided

# **CURRENTLY AND FUTURE SUPPORTED STANDARDS open**PASS **OpenSCENARIO**<sup>®</sup> OSI bringing content to the road **Open Simulation Interface** openPASS fmi OpenDRIVE<sup>®</sup> managing the road ahead FUNCTIONAL MOCK•UP INTERFACE

# **PLATFORM STRUCTURE**





# **PLATFORM STRUCTURE**





### SIMULATION PROCESS USER PERSPECTIVE





### USE CASE TRAFFIC-SCENARIO SIMULATION



#### Features:

- Closed loop simulation of traffic scenarios
- Stochastic variation of the scenarios
- Intervention through detection of events and triggered actions
- Faster-than-real-time execution of the simulation

#### Example: AEB intervention triggered by passive cut-in manoeuvre

- Highway scenario with random surrounding traffic
- Ego vehicle with simple AEB system and abstract sensors
- Time-based event trigger
- Trajectory controlled lane change for scenario vehicle



### USE CASE CRASH RE-SIMULATION



#### Features:

- Create configuration files from GIDAS-PCM accident scenario database
- Stochastic variation of the scenarios (positions, velocities)
- Basis components for re-simulation: sensor, trajectory follower, two track vehicle model, impact calculation
- Store results in csv files in case folders

#### Example question: How many selected cases could be avoided by a AEB function?



## **EXEMPLARY SIMULATION RESULTS**



#### Traffic-scenario simulation

AEB intervention triggered by passive cut-in manoeuvre

#### Crash re-simulation from GIDAS-PCM case

Oncoming collision at intersection (LTAP – "left turn across path") with post-crash behaviour



### TIMELINE





## CONCLUSION



- openPASS is an open source platform for effectiveness assessment of advanced driver assistance systems and automated driving
- Open source platform for high level of acceptance and transparency
- Modular structure for easy platform extension und inclusion of user-specific models
- Support for standards and standardized interfaces for a flexible simulation setup
- Exemplary applications of openPASS:



Crash re-simulation



Traffic-scenario simulation

# **PARTICIPATION IN THE WORKING GROUP**



#### Membership Privileges

Privilege	Driver Member	User Member	Service Provider Member	Project Manager
Steering Committee	Х	Elected	Elected	-
Architecture Committee	Х	-	-	x
Quality Committee	Х	Elected	Elected	Х
GeneralAssembly	Х	Х	Х	-



The company should be at least an Eclipse Solution Member

- Networking and learning
- The annual membership fee for Solutions Members is tiered based on revenue



Working Group participation agreement

- Contribution in development of openPASS
- Discussion of the roadmap
- Active collaboration with the working group

For more information, look at the openPASS charter:

https://www.eclipse.org/org/workinggroups/openpasswg\_charter.php

# **COMMUNICATION WITH THE WORKING GROUP**









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